

MLFB-Ordering data

6SL3210-1KE18-8AP1



Figure similar

Client order no. :
Order no. :
Offer no. :
Remarks ·

Item no. :
Consignment no. :
Project :

Rated da	General tech. specifications				
Input		Power factor λ	0.	70 0.85	
Number of phases	3 AC	Offset factor cos φ	0.	95	
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.	97	
Line frequency	47 63 Hz	Sound pressure level (1m)	52	2 dB	
Rated current (LO)	11.40 A	Power loss	0.	15 kW	
Rated current (HO)	10.60 A	Amhian	nt conditio		
Output		Ambier		ons	
Number of phases	3 AC	Cooling	Air coolir	ng using an integrated fan	
Rated voltage	400 V	Cooling of requirement	0.005 m	312 (0 177 ft312)	
Rated power IEC 400V (LO)	4.00 kW	Cooling air requirement		³ /s (0.177 ft ³ /s)	
Rated power NEC 480V (LO)	5.00 hp	Installation altitude	1000 m ((3280.84 ft)	
Rated power IEC 400V (HO)	3.00 kW	Ambient temperature			
Rated power NEC 480V (HO)	4.00 hp	Operation	-10 40) °C (14 104 °F)	
	·	Transport	-40 70) °C (-40 158 °F)	
Rated current (IN)	9.00 A	Storage	-40 70) °C (-40 158 °F)	
Rated current (LO)	8.80 A	Relative humidity			
Rated current (HO)	7.30 A				
Max. output current	14.60 A	Max. operation		5 % At 40 °C (104 °F), condensation nd icing not permissible	
Pulse frequency	4.000 kHz				
Output frequency for vector control	0 240 Hz	Closed-loop o	control tec	hniques	
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / parame	eterizable	Yes	
		V/f with flux current control (F0	CC)	Yes	
		V/f ECO linear / square-law		Yes	
		Companya and a second second second		Vec	

Overload capability

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

Communication

Communication

Sensorless vector control

Vector control, with sensor

Encoderless torque control

Torque control, with encoder

PROFIBUS DP

Yes

No

No

No



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Mechanical	data		Cc
Degree of protection	IP20 / UL open type	Signal cable	
Size	FSA	Conductor cross-s	ection
Net weight	1.70 kg (3.75 lb)	Line side	
Width	73 mm (2.87 in)	Version	
Height	196 mm (7.72 in)	Conductor cross-section	
Depth	203 mm (7.99 in)	Motor end	
Inputs / out	puts	Version	
tandard digital inputs	-	Conductor cross-section	
Number	6	DC link (for braking resisted	or
Switching level: 0→1	11 V	Version	
Switching level: 1→0	5 V	Conductor cross-section	
Max. inrush current	15 mA	Line length, max.	
ail-safe digital inputs		PE connection	
Number	1	Max. motor cable length	
Digital outputs		Shielded	
Number as relay changeover contact	1	Unshielded	
Output (resistive load)	DC 30 V, 0.5 A		S
Number as transistor	1	Compliance with standards	
Output (resistive load)	DC 30 V, 0.5 A		
nalog / digital inputs		CE marking	
Number	1 (Differential input)		
Resolution	10 bit		
witching threshold as digital in	out		
0→1	4 V		
1→0	1.6 V		
Analog outputs			
Number	1 (Non-isolated output)		
PTC/ KTY interface			
1 motor temperature sensor input, sensor	rs that can be connected: PTC, KTY		
and Thermo-Click, accuracy ±5 °C			



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Converter losses to EN 50598-2* Efficiency class IE2 Comparison with the reference converter (90% / -65.57 % 100%) -**O**-^{134.0 W (2.20 %)} 98.0 W (1.60 %) 111.0 W (1.83 %) 100% 72.0 W (1.18 %) 78.0 W (1.28 %) 86.0 W (1.42 %) 50% 62.0 W (1.02 %) 65 W (1.06 %) 25% f 50% 90% The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values