

# **MLFB-Ordering data**

6SL3210-1KE23-2UB1



Client order no. : Item no. :
Order no. : Consignment no. :
Offer no. : Project :
Remarks :

Rated data		General tech. specifications		
nput		Power factor λ	0.7	'0 0.85
Number of phases	3 AC	Offset factor cos φ	0.9	95
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.9	7
Line frequency	47 63 Hz	Sound pressure level (1m)	66	dB
Rated current (LO)	40.60 A	Power loss	0.4	3 kW
Rated current (HO)	36.40 A	Ambient conditions		
Output		Alliblei	it condition	112
Number of phases	3 AC	Cooling	Air coolin	g using an integrated f
Rated voltage	400 V	Caaling air vasuiramant	0.010 3	lo (0 626 ft3lo)
Rated power IEC 400V (LO)	15.00 kW	Cooling air requirement	0.018 m³/s (0.636 ft³/s) 1000 m (3280.84 ft)	
Rated power NEC 480V (LO)	20.00 hp	Installation altitude	1000 m (	3280.84 ft)
Rated power IEC 400V (HO)	11.00 kW	Ambient temperature		
Rated power NEC 480V (HO)	15.00 hp	Operation		°C (14 104 °F)
Rated current (IN)	32.00 A	Transport		°C (-40 158 °F)
Rated current (LO)	31.00 A	Storage	-40 70	°C (-40 158 °F)
Rated current (HO)	25.00 A	Relative humidity		
Max. output current	50.00 A	Max. operation	95 % At 40 °C (104 °F), condense and icing not permissible	
Pulse frequency	4.000 kHz			
Output frequency for vector control	0 240 Hz	Closed-loop o	ontrol tec	hniques
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / parame	terizable	Yes
		V/f with flux current control (FC	C)	Yes
		V/f ECO linear / square-law		Yes
Overload capability		Sensorless vector control		Yes
Low Overload (LO)  150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time		Vector control, with sensor		No
		Encoderless torque control		No
High Overload (HO)	Torque control, with encoder		No	

300 s cycle time

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a

Communication

Communication

RS485



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03	L3210-1RE23-20B1		Figure s	
Mechanical data		Co	Connections	
Degree of protection	IP20 / UL open type	Signal cable		
Size	FSC	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 1	
Net weight	4.40 kg (9.70 lb)	Line side		
Width	140 mm (5.51 in)	Version	Plug-in screw terminals	
Height	295 mm (11.61 in)	Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG	
Depth	203 mm (7.99 in)	Motor end		
Inputs / outputs		Version	Plug-in screw terminals	
tandard digital inputs		Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG	
Number	6	DC link (for braking resistor)	)	
Switching level: 0→1	11 V	Version	Plug-in screw terminals	
Switching level: 1→0	5 V	Conductor cross-section	6.00 16.00 mm² (AWG 10 AWG	
Max. inrush current	15 mA	Line length, max.	15 m (49.21 ft)	
ail-safe digital inputs		PE connection	On housing with M4 screw	
Number	1	Max. motor cable length		
igital outputs		Shielded	150 m (492.13 ft)	
Number as relay changeover contact	1	Unshielded	150 m (492.13 ft)	
Output (resistive load)	DC 30 V, 0.5 A	S	Standards	
Number as transistor	1	Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Output (resistive load)	DC 30 V, 0.5 A		EMS D: v: 2004/400/ES   V	
nalog / digital inputs		CE marking	EMC Directive 2004/108/EC, Low-Vol Directive 2006/95/EC	
Number	1 (Differential input)			
Resolution	10 bit			
witching threshold as digital in	put			
0→1	4 V			
1→0	1.6 V			

# PTC/ KTY interface

**Analog outputs** 

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^{\circ}\text{C}$ 

1 (Non-isolated output)



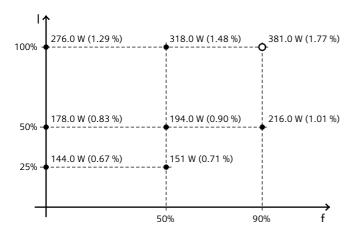
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Figure similar

### Converter losses to EN 50598-2\*

Efficiency class	IE2
Comparison with the reference converter (90% /	-65.83 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values