

MLFB-Ordering data

6SL3210-1KE21-3UB1



Figure similar

Client order no. : Order no. : Offer no. : Remarks :

| ltem no. : |
|-------------------|
| Consignment no. : |
| Project : |

| Rated data | | General tech. specifications | | |
|--|-----------------------|-----------------------------------|-------------------------------------|--|
| Input | | Power factor λ | 0.70 0.85 | |
| Number of phases | 3 AC | Offset factor cos φ | 0.95 | |
| Line voltage | 380 480 V +10 % -20 % | Efficiency η | 0.97 | |
| Line frequency | 47 63 Hz | | 63 dB | |
| Rated current (LO) | 16.50 A | Sound pressure level (1m) | | |
| Rated current (HO) | 12.80 A | Power loss | 0.18 kW | |
| Output | | Ambient conditions | | |
| Number of phases | 3 AC | Cooling | Air cooling using an integrated fan | |
| Rated voltage | 400 V | | | |
| Rated power IEC 400V (LO) | 5.50 kW | Cooling air requirement | 0.009 m³/s (0.318 ft³/s) | |
| Rated power NEC 480V (LO) | 7.50 hp | Installation altitude | 1000 m (3280.84 ft) | |
| Rated power IEC 400V (HO) | 4.00 kW | Ambient temperature | | |
| Rated power NEC 480V (HO) | 5.00 hp | Operation | -10 40 °C (14 104 °F) | |
| Rated current (IN) | 13.00 A | Transport | -40 70 °C (-40 158 °F) | |
| Rated current (LO) | 12.50 A | Storage | -40 70 °C (-40 158 °F) | |
| | | Relative humidity | | |
| Rated current (HO) | 8.80 A | 95 % At 40 °C (104 °F), con | | |
| Max. output current | 17.60 A | Max. operation | and icing not permissible | |
| Pulse frequency | 4.000 kHz | | | |
| Output frequency for vector control | 0 240 Hz | Closed-loop control techniques | | |
| Output frequency for V/f control | 0 550 Hz | V/f linear / square-law / parame | terizable Yes | |
| | | V/f with flux current control (FC | CC) Yes | |
| | | V/f ECO linear / square-law | Yes | |
| Overload capability | | Sensorless vector control | Yes | |
| Low Overload (LO) | | Vector control, with sensor | No | |
| 150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a | | Encoderless torque control | No | |

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

Communication

Communication

Torque control, with encoder

RS485

No



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Figure similar

| Mechanical data | | Figure similar Connections | |
|--|------------------------------------|--------------------------------|--|
| Degree of protection | IP20 / UL open type | Signal cable | |
| Size | FSB | Conductor cross-section | 0.15 1.50 mm² (AWG 24 AWG 16) |
| Net weight | 2.30 kg (5.07 lb) | Line side | |
| Width | 100 mm (3.94 in) | Version | Plug-in screw terminals |
| Height | 196 mm (7.72 in) | Conductor cross-section | 4.00 6.00 mm² (AWG 12 AWG 10) |
| Depth | 203 mm (7.99 in) | Motor end | |
| Inputs / out | puts | Version | Plug-in screw terminals |
| Standard digital inputs | | Conductor cross-section | 4.00 6.00 mm² (AWG 12 AWG 10) |
| Number | 6 | DC link (for braking resistor) |) |
| Switching level: 0→1 | 11 V | Version | Plug-in screw terminals |
| Switching level: 1→0 | 5 V | Conductor cross-section | 4.00 6.00 mm² (AWG 12 AWG 10) |
| Max. inrush current | 15 mA | Line length, max. | 15 m (49.21 ft) |
| Fail-safe digital inputs | | PE connection | On housing with M4 screw |
| Number | 1 | Max. motor cable length | J |
| Digital outputs | | Shielded | 150 m (492.13 ft) |
| Number as relay changeover contact | 1 | Unshielded | 150 m (492.13 ft) |
| Output (resistive load) | DC 30 V, 0.5 A | S | tandards |
| Number as transistor | 1 | Compliance with standards | UL, cUL, CE, C-Tick (RCM) |
| Output (resistive load) | DC 30 V, 0.5 A | | |
| Analog / digital inputs | | CE marking | EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC |
| Number | 1 (Differential input) | | |
| Resolution | 10 bit | | |
| Switching threshold as digital input | | | |
| 0→1 | 4 V | | |
| 1→0 | 1.6 V | | |
| Analog outputs | | | |
| Number | 1 (Non-isolated output) | | |
| PTC/ KTY interface | | | |
| 1 motor temperature sensor input, sensor and Thermo-Click, accuracy ±5 °C | rs that can be connected: PTC, KTY | | |



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Figure similar

Converter losses to EN 50598-2* Efficiency class IE2 Comparison with the reference converter (90% / -66.06 % 100%) -**O**-^{177.0 W (2.04 %)} 132.0 W (1.52 %) 150.0 W (1.73 %) 100% 87.0 W (1.01 %) 94.0 W (1.09 %) 104.0 W (1.20 %) 50% 73.0 W (0.84 %) 76 W (0.88 %) 25% f 50% 90%

The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values